

WEST Search History

DATE: Tuesday, March 17, 2009

Hide? Set Name Query

Hit Count

DB=USPT; PLUR=YES; OP=ADJ

| | | | |
|--------------------------|-----|--|----|
| <input type="checkbox"/> | L90 | foot and L89 | 17 |
| <input type="checkbox"/> | L89 | float\$4 and L88 | 18 |
| <input type="checkbox"/> | L88 | "0" and L87 | 71 |
| <input type="checkbox"/> | L87 | robot\$6 and L86 | 92 |
| <input type="checkbox"/> | L86 | L85 and zmp (700/245 l700/246 l700/251 l700/253 l700/260 l700/261 318/568.1 l 318/568.12 l318/568.16 l318/568.17 l318/568.2 901/1 l901/9 l901/46 180.1).ccls. | 92 |
| <input type="checkbox"/> | L84 | (("6962220")!.PN.) .p67-p150. | 1 |

DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ

| | | | |
|--------------------------|-----|--|------|
| <input type="checkbox"/> | L83 | robot\$6 and (walk\$3 or biped or humanoid or two legged) and (inlina\$6 or betn or tilt or deviat\$5 or obliqu\$5 or indirect\$4 or change direction or slope or slant) | 6273 |
| <input type="checkbox"/> | L82 | ('6711469' l'6697709' l'6567724' l'6505098' l'6493606' l'6480761' l'6330494' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU. | 16 |
| <input type="checkbox"/> | L81 | marc.xa. and legged and inclination | 35 |
| <input type="checkbox"/> | L80 | marc.xa. and legged and inclinaiton | 0 |
| <input type="checkbox"/> | L79 | ('5404086')!.ABPN1,NRPN,PN,TBAN,WKU. | 2 |
| <input type="checkbox"/> | L78 | (edding or updating) and (motion or traject\$4 or movement) and zmp and robot\$6 | 27 |
| <input type="checkbox"/> | L77 | (edding or updating) same (motion or traject\$4 or movement) and zmp and robot\$6 | 12 |
| <input type="checkbox"/> | L76 | (edding or updating) same (motion or traject\$4 or movement) and L75 | 10 |
| <input type="checkbox"/> | L75 | robot and zmp and yaw | 169 |
| <input type="checkbox"/> | L74 | marc.xa. and zmp | 47 |
| <input type="checkbox"/> | L73 | 10/181500 | 3 |

| | | | |
|--------------------------|---|--|---------|
| <input type="checkbox"/> | L72 | ('6697709' l'6289265' l'6243623')!.ABPN1,NRPN,PN,TBAN,WKU. | 6 |
| <input type="checkbox"/> | L71 | marc.xa. and robot and zmp | 47 |
| <input type="checkbox"/> | L70 | (motions or movement or displacement) and L69 | 122 |
| <input type="checkbox"/> | L69 | computer and L68 | 135 |
| <input type="checkbox"/> | L68 | record\$3 and L67 | 135 |
| <input type="checkbox"/> | L67 | (request or command) and L66 | 166 |
| <input type="checkbox"/> | L66 | L62 and L65 | 174 |
| <input type="checkbox"/> | L65 | execut\$5 and L64 | 311708 |
| <input type="checkbox"/> | L64 | run or L62 | 1387159 |
| | | (6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn. | 98 |
| <input type="checkbox"/> | L62 | (similar or "same") function and L61 | 201 |
| <input type="checkbox"/> | L61 | robot and control software and (chang\$3 or replac\$5) | 2157 |
| <input type="checkbox"/> | L60 | ('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU. | 2 |
| <input type="checkbox"/> | L59 | (10/126774 l 10/970977 l 10/935607 l 10/919172 l 10/775845 l 10/732446 l 10/726597 l 10/683496 l 10/637890) | 18 |
| <input type="checkbox"/> | L58 | (motion or displacement or trajector\$3) and L57 | 116 |
| <input type="checkbox"/> | L57 | (humanoid or two legged robot and human like robot) and zmp and comput\$5 | 119 |
| <input type="checkbox"/> | L56 | zmp and "approximately 0" | 20 |
| | <i>DB=PGPB,USPT; PLUR=YES; OP=ADJ</i> | | |
| <input type="checkbox"/> | L55 | ((20060106495")!.PN.).PGPB. l ((7119510")!.PN.).USPT. | 2 |
| | <i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i> | | |
| <input type="checkbox"/> | L54 | grasping and L53 | 6 |
| <input type="checkbox"/> | L53 | horizontal and vertical and L52 | 20 |
| <input type="checkbox"/> | L52 | signal and detection and L51 | 20 |
| <input type="checkbox"/> | L51 | distance and L50 | 23 |

| | | | |
|---|-----|--|-----|
| <input type="checkbox"/> | L50 | center and L49 | 28 |
| <input type="checkbox"/> | L49 | motion and L48 | 30 |
| <input type="checkbox"/> | L48 | gravity and L47 | 31 |
| <input type="checkbox"/> | L47 | floor reaction and L46 | 37 |
| <input type="checkbox"/> | L46 | foot and robot and ground contact and sensor and sole and joint and reaction and force and walk\$3 | 55 |
| <i>DB=PGPB; PLUR=YES; OP=ADJ</i> | | | |
| <input type="checkbox"/> | L45 | L44 | 1 |
| <i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i> | | | |
| <input type="checkbox"/> | L44 | 10/553278 | 1 |
| <input type="checkbox"/> | L43 | L42 and robot | 13 |
| <input type="checkbox"/> | L42 | metatarsophalangeal | 538 |
| <input type="checkbox"/> | L41 | ground and contact and L39 | 26 |
| <input type="checkbox"/> | L40 | groung and contact and L39 | 0 |
| <input type="checkbox"/> | L39 | sensor and L38 | 34 |
| <input type="checkbox"/> | L38 | axis and L37 | 34 |
| <input type="checkbox"/> | L37 | soles and L36 | 34 |
| <input type="checkbox"/> | L36 | foot and L35 | 39 |
| <input type="checkbox"/> | L35 | L34 and coordinate | 39 |
| <input type="checkbox"/> | L34 | position and orientation and L33 | 44 |
| <input type="checkbox"/> | L33 | (L5 or L6) and L32 | 85 |
| <input type="checkbox"/> | L32 | landed and landing and foot and robot\$6 | 153 |
| <input type="checkbox"/> | L31 | landed and landing and foot and footstep and robot\$6 | 6 |
| <input type="checkbox"/> | L30 | landed and landing and foot and footstep and (L5 or L6) | 3 |
| <input type="checkbox"/> | L29 | landded and landing and foot and footstep and (L5 or L6) | 0 |
| <input type="checkbox"/> | L28 | landded and landing and foot and footstep and L19 | 0 |
| <input type="checkbox"/> | L27 | landded and landing and foot and L26 | 0 |
| <input type="checkbox"/> | L26 | posture and L25 | 52 |
| <input type="checkbox"/> | L25 | gravity and coordinate and L24 | 53 |
| <input type="checkbox"/> | L24 | estimat\$3 and position and L23 | 62 |
| <input type="checkbox"/> | L23 | dynamics same model and L20 | 74 |

| | | | |
|--------------------------|-----|---|---------|
| <input type="checkbox"/> | L22 | dyanamics and L20 | 0 |
| <input type="checkbox"/> | L21 | dyanamics same model and L20 | 0 |
| <input type="checkbox"/> | L20 | L18 and L19 | 184 |
| <input type="checkbox"/> | L19 | movement or trajectory and L18 | 2691502 |
| <input type="checkbox"/> | L18 | floor and zmp and L5 | 193 |
| <input type="checkbox"/> | L17 | floor and zmp and L16 (5024920 l 5173382 l 5490103 l 5557564 l 5901829 l 6201488 l 6521838 l 6518503 l 6695663 l 6592418 l 5733819 l 6027554 l 6663326 l 6694847 l 6685863 l 4252414 l 4588518 l 4561746 l 4719331 l 5118090 l 5434926 l 5419740 l 5558196 l 5527940 l 5716481).pn. | 0 |
| <input type="checkbox"/> | L16 | | 47 |
| <input type="checkbox"/> | L15 | motion pattern and L13 | 2 |
| <input type="checkbox"/> | L14 | motion pattern and stor\$3 and L13 | 0 |
| <input type="checkbox"/> | L13 | freedom and L12 | 5 |
| <input type="checkbox"/> | L12 | L10 and L11 | 6 |
| <input type="checkbox"/> | L11 | L10 and gait or gate (6580969' l 6493606' l 6463356' l 6289265' l 6243623' l 5872893' | 1272034 |
| <input type="checkbox"/> | L10 | l 5841258' l 5838130' l 5594644' l EP 1136193A' l EP 1103451A'!.ABPN1, NRPN,PN,TBAN,WKU. | 18 |
| <input type="checkbox"/> | L9 | (20030019671' l 20020138359' l 6591923' l 6458011'!.ABPN1,NRPN,PN, TBAN,WKU. | 7 |
| <input type="checkbox"/> | L8 | (legged robot or pet robot or humanoid near10 robot) motion and pattern | 13 |
| <input type="checkbox"/> | L7 | (legged robot or pet robot or humanoid near10 robot) motion and pattern and L6 (6252544 l 6493606 l 6243623 l 6289265 l 5673367 l 5355064 l 5455497 l 5325031 l 5357433 l 5594644 l 6580969 l 6718231 l 5504841 l 5842533 l 4621333 l 4633059 l 4987527 l 5937398 l 6064168 l 6429812 l 6584377 l 5259064 l 5349646 l 5946041 l 4540211 l 4762261 l 5273296 l 5616917 l 5627440 l 5794621 l 6059092 l 6059092 l 6068201 l 6456728 l 6505098 l 6711469 l 5402050 l 5525883 l 5841258 l 6463356 l 4614504 l 5040626 l 5343397 l 5369346 l 5378969 l 5644204 l 5672924 l 5838130 l 5872893 l 6229552).pn. | 0 |
| <input type="checkbox"/> | L6 | (700/245 l 700/246 l 700/251 l 700/253 l 700/260 l 700/261 or 318/568.1 l 318/568.12 l 318/568.16 l 318/568.17 l 318/568.2 or 901/1 l 901/9 l 901/46 or 180/8.1 l 180/8.6 l 180/65.1 or 701/23 or 320/116 l 320/120 or 446/376 l 446/384).ccls. | 97 |
| <input type="checkbox"/> | L5 | | 10672 |
| <input type="checkbox"/> | L4 | 6580969.pn. | 2 |

| | | | |
|--------------------------|----|-------------|---|
| <input type="checkbox"/> | L3 | 11/456454 | 2 |
| <input type="checkbox"/> | L2 | 10/511608 | 1 |
| <input type="checkbox"/> | L1 | 6920374.pn. | 2 |

END OF SEARCH HISTORY